

BILINEAR TRANSFORMATIONS

Conformal Mapping

A function $w = f(z)$ is said to be conformal at z_0 if curve -in the z - plane passing through z_0 & image curve in w -plane passing $f(z_0)$ preserves the angle in magnitude & sense of rotation (orientation) of angle.

Theorem

Let $f \in H(D)$ i.e, analytic on D & $z_0 \in D$ such that $f'(z_0) \neq 0$. Then f is conformal at z_0 .

Example

$f(z) = e^z$ is conformal everywhere since e^z is an entire function & $f'(z) = e^z \neq 0 \forall z \in \mathbb{C}$.

Critical Point

If f is non constant analytic at z_0 & $f'(z_0) = 0$, then the conformal character fails at z_0 , such a point z_0 is called a critical point of f .

Example

Consider $w = f(z) = \sin z$ since $f(z)$ is entire, so for every $z_0 \in \mathbb{C}$ is a regular point $\Rightarrow z = k\pi: k \in \mathbb{Z}$ are critical points of $f(z)$.

Bilinear/ Linear Fractional/ Mobius Transformation

The map

$$w = \frac{az + b}{cz + d}, \quad ad - bc \neq 0 \quad (i)$$

Where a, b, c & d are complex constants, is called a linear fractional transformation, or Mobius transformation & equation (i) can also be written as

$$Azw + bz + cz + D = 0, \quad (AD - BC \neq 0)$$

and vice versa.

Note

A mobius transformation is simply a composition of one, some or all of the following special types of transformation.

- **Translation:** It is a map of the form $z \mapsto z + \alpha, \alpha \in \mathbb{C} \setminus \{0\}$. If $\alpha = 0$ then it is an identity.

- **Magnification or Contraction:** It is a map of the form $z \mapsto rz, r \in \mathbb{R} - \{0\}$. For $r = 1$, this is the identity map & for $r = 0$ it is a constant map.
 Case (i) When $r > 1$, then this is a "magnification".
 Case (ii) When $r < 1$, then this is a contraction map.

Note

If $r < 0$ then $w = rz$ gives the reflection through the origin followed by such a "magnification" or shrinking/contraction depending on $r < -1$ or $-1 < r < 0$.

- **Rotation:** It is a map of the form $z \mapsto e^{i\theta}z; \theta \in \mathbb{R}$. This map produces a rotation through an angle about the origin with positive sense, $\theta > 0$.

Note

The rotation coupled with magnification is referred to as Dilation: $z \mapsto az (a \neq 0)$.

- **Inversion:** It is a map of the form $z \mapsto \frac{1}{z}$ which produces a geometric inversion (or reciprocal map or the inversion map.)

Remark

- ❖ If we let $T(z) = T_{abcd}(z)$ & if $\alpha \in \mathbb{C} \setminus \{0\}$, then $a\alpha, ab, ac, ad$ correspond to the same mobius transformation as

$$T_{abcd}(z) = T_{(a\alpha)(b\alpha)(c\alpha)(d\alpha)}(z)$$

i.e., behavior of T does not change when a, b, c, d are multiplied by a non-zero constant.

- ❖ The mobius transformation $T(z)$ is analytic on $\mathbb{C} \setminus \{d/c\}$.
- ❖ If $c = 0$ then $T(z) = \frac{az+b}{cz+d}, ad - bc \neq 0$ reduces to $T(z) = \frac{a}{d}z + \frac{b}{d} = \alpha z + \beta (ad \neq 0, \alpha \neq 0)$ & called a linear map.
- ❖ Every mobius transformation $T(z), T(z) = \frac{az+b}{c+d}, ad - bc \neq 0$, can be decompose as

$$\begin{aligned}
 T(z) &= \left[a \left(z + \frac{d}{c} \right) + b - \frac{ad}{c} \right] \frac{1}{c \left(z + \frac{d}{c} \right)} \\
 &= \frac{a}{c} - \left(\frac{ad - bc}{c^2} \right) \frac{1}{\left(z + \frac{d}{c} \right)}, c \neq 0
 \end{aligned}$$

- ❖ If $ad - bc = 0$ then $T(z)$ is a constant map

Fixed Point

Let D be a subset of \mathbb{C}_∞ and $f: D \rightarrow \mathbb{C}_\infty$. A point $z_0 \in D$ is said to be a fixed point of f if $f(z_0) = z_0$. The set of all fixed points of f is denoted by **Fix** (f)

Examples

- The function $f(z) = z^2$ has exactly three fixed points, namely, 0,1 and ∞ whereas the function $f(z) = z^{-1}$ has two fixed points namely 1 and -1 .
- The function $f(z) = z - 1$ has no fixed points in \mathbb{C} whereas it has one fixed point in \mathbb{C}_∞ , namely the point at ∞
- The function $f(z) = \frac{iz}{|z|}, z \neq 0$, has no fixed points in $\mathbb{C} \setminus \{0\}$

Note

- ❖ Every non-constant real-valued continuous function $f: (-1,1) \rightarrow (-1,1)$ has a fixed point in $(-1,1)$. – However, a similar result does not hold for functions $f: \Delta \rightarrow \Delta, |\alpha| = 1$, defined by

$$\phi_\alpha(z) = \frac{z - \alpha}{1 - \bar{\alpha}z}$$

has no fixed points in Δ .

Proposition

Every Mobius transformation $T: \mathbb{C}_\infty \rightarrow \mathbb{C}_\infty$ has at most two fixed points in \mathbb{C}_∞ unless $T(z) \equiv z$. Equivalently, if a Mobius transformation leaves three points in \mathbb{C}_∞ fixed, then it is none other than the identity function.

Corollary

If S and T are two Mobius transformations which agree at three distinct points of \mathbb{C}_∞ , then $S = T$.

Results

- ❖ Every mobius transformation maps circles and straight lines into circles and straight lines.
- ❖ Every Mobius transformation maps circles in \mathbb{C}_∞ onto circles in \mathbb{C}_∞ .
- ❖ Under translation, magnification (scaling) & rotation, circles maps to circles & lines to lines.
- ❖ Under the function $w = \frac{1}{z}$, we have
 - The image of a line through the origin is a line through the origin.
 - The image of a line not through the origin is a circle through the origin.
 - The image of a circle through the origin is a line not through the origin.
 - The image of a circle not through the origin is a circle not through the origin.

Classification of Bilinear Transformation-on the basis of Normal Form

Let $w = T(z) = \frac{az+b}{cz+d}$ be a bilinear transformation.

Parabolic: The bilinear transformation with one fixed point is called parabolic i.e., $(a - d)^2 + 4bc = 0$.

Elliptic: A bilinear transformation with two fixed points i.e., $(a - d)^2 + 4bc \neq 0$ such that $|k| = 1, k \neq 1$ is said to be elliptic i.e., in the normal form k is of the form $k = e^{i\alpha}, \alpha \neq 0$.

Hyperbolic: A bilinear transformation with two fixed points i.e., $(a - d)^2 + 4bc \neq 0$ & $k > 0, k \in \mathbb{R}$ is termed as hyperbolic.

Loxodromic: A bilinear transformation that is neither hyperbolic, elliptic, nor parabolic is called loxodromic, i.e., it has two fixed points & satisfies the condition $k = \alpha e^{i\alpha}, \alpha \neq 0, \alpha \neq 1$.

Cross Ratio

For the set of three distinct points z_1, z_2, z_3 of \mathbb{C}_∞ , the expression $\frac{(z-z_1)(z_2-z_3)}{(z-z_3)(z_2-z_1)} = \frac{(z-z_1)/(z-z_3)}{(z_2-z_1)/(z_2-z_3)}$ is called the cross-ratio of the four points z, z_1, z_2, z_3 & is denoted by (z, z_1, z_2, z_3) .

Symmetric Point/Inverse Point

Let L be a line in \mathbb{C} . Two point a & a^* in \mathbb{C} are said to be symmetric with respect to L if L is the perpendicular bisector of $[a, a^*]$ the line segment connecting a & a^* .

Examples:

- (i) Two points z & z^* are symmetric w.r.t. the real axis when $z^* = \bar{z}$.
- (ii) Two points z & z^* are symmetric w.r.t. the imaginary axis iff $z^* = -\bar{z}$

Suppose that k is a circle $|z - z_0| = r$ in \mathbb{C} . Two points a & a^* are said to be symmetric w.r.t. circle k (or inverse points w.r.t. the circle k) iff $|a - z_0||a^* - z_0| = r^2$ & $\text{Arg}(a - z_0) = \text{Arg}(a^* - z_0)$. i.e., a & a^* on the same ray emanating from the centre z_0 of k , & the product of their distances from the centre of the circle k is equal to the square of the radius of the circle.

MATHSEON